

① If ϕ is a differentiable scalar field,

Then ~~$\vec{\nabla} \times (\vec{\nabla} \times \phi)$~~ $\vec{\nabla} \times (\vec{\nabla} \phi) = 0$

Sol.

$$\vec{\nabla} \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$$\vec{\nabla} \times (\vec{\nabla} \phi) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial^2 \phi}{\partial y \partial z} - \frac{\partial^2 \phi}{\partial z \partial y} \right) + \hat{j} \left(\frac{\partial^2 \phi}{\partial z \partial x} - \frac{\partial^2 \phi}{\partial x \partial z} \right) + \hat{k} \left(\frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} \right) = 0$$

[~~∴ $\vec{\nabla} \times (\vec{\nabla} \times \phi)$ We assume~~
A has continuous 2nd order partial derivatives]

① $\nabla \cdot (\nabla \times \vec{A}) = 0$ where \vec{A} is a differentiable vector field.

~~$\nabla \cdot (\nabla \times \vec{A}) =$~~

Sol: Let $\vec{A} = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$

$$\nabla \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \hat{j} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \hat{k} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right)$$

$$\nabla \cdot (\nabla \times \vec{A})$$

$$= \frac{\partial}{\partial x} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \frac{\partial}{\partial z} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right)$$

$$= \frac{\partial^2 A_3}{\partial x \partial y} - \frac{\partial A_2}{\partial x \partial z} + \frac{\partial^2 A_1}{\partial y \partial z} - \frac{\partial^2 A_3}{\partial y \partial x} + \frac{\partial^2 A_2}{\partial z \partial x} - \frac{\partial^2 A_1}{\partial z \partial y}$$

= 0 [We assume \vec{A} has continuous 2nd order partial derivatives]

② ~~$\nabla \cdot (\nabla \times \vec{A}) =$~~ If \vec{A} is a differentiable vector field then

$$\nabla \times (\nabla \times \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A} \quad \text{Where}$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

Sol: [H.W]

$\vec{\nabla} \cdot \vec{\nabla} = \nabla^2 \equiv \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$ is called
Laplacian operator.

If ϕ and ψ are two differentiable scalar
fields then.

~~$\vec{\nabla} \cdot (\phi \vec{\nabla} \psi)$~~ $\vec{\nabla} \cdot (\phi \vec{\nabla} \psi - \psi \vec{\nabla} \phi) = \phi \nabla^2 \psi - \psi \nabla^2 \phi$

Sol: $\vec{\nabla} \cdot (\phi \vec{\nabla} \psi) = \vec{\nabla} \phi \cdot \vec{\nabla} \psi + \phi \nabla^2 \psi$

$$\vec{\nabla} \cdot (\psi \vec{\nabla} \phi) = \vec{\nabla} \psi \cdot \vec{\nabla} \phi + \psi \nabla^2 \phi$$

$$\therefore \vec{\nabla} \cdot (\phi \vec{\nabla} \psi - \psi \vec{\nabla} \phi) = (\phi \nabla^2 \psi - \psi \nabla^2 \phi)$$